

# Quasi-Lipschitz Conditions in Vorticity Transport

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*Abstract:* - Since vorticity transport is becoming a more and more important tool in recent numerical approaches to fluid flow problems, there is some interest in the study of approximations to its basic equation. In the joint paper [18] with V. Solonnikov, using quasi-Lipschitz conditions, we have shown that Helmholtz's vorticity transport equation with partial discretization has a unique classical solution in smoothly bounded 3-dimensional domains on each bounded interval of time. This solution depends continuously on its initial value and, in addition, fulfils a discretized form of Cauchy's vorticity equation.

*Key-Words:* - Helmholtz equation, vorticity

## 1 Introduction

The use of vorticity transport in mathematical models of incompressible flow problems is taking its advantage from the regularization being implied in the reconstruction of the flow velocity  $v$  from its vorticity  $w = \text{rot } v$ : We get  $v$  from the boundary value problem

$$\text{rot } v = w, \quad \text{div } v = 0 \quad \text{in } \Omega, \quad (1)$$

$$v \cdot N = 0 \quad \text{on } \partial\Omega \quad (2)$$

in a bounded simply connected domain  $\Omega \subset \mathbb{R}^3$  with boundary  $S = \partial\Omega \in C^{2+\alpha}$ ,  $\alpha \in (0, 1)$ ;  $N(x)$  denotes the exterior normal to  $S$  at the point  $x$ . It is well known from the vector potential theory that problem (1), (2) admits a unique solution

$$v = Kw \quad (3)$$

for arbitrary divergence free  $w \in C^0(\bar{\Omega})$  satisfying the compatibility conditions

$$\int_{S_k} w \cdot N \, ds = 0, \quad k = 0, \dots, h, \quad (4)$$

where  $S_k$  are the connected components of  $S$  ( $S_0$  is the exterior and  $S_1, \dots, S_h$  are the interior boundaries), and the operator  $K$  (being of Biot-Savart type) can be defined also in the case of multi-connected domains, c.p. [17] and the citations there.

The important question, whether we will arrive at a fluid flow having unique particles' paths may be settled by requiring a spatial Lipschitz condition for the velocity field  $v$  from (1), (2). However, as shown

in potential theory [4], this would require Hölder-continuity of  $w$  with respect to its spatial coordinates. A more natural picture would be given by bounds only for the sup-norm  $|w(t, \cdot)|_0 = \sup_{x \in \Omega} |w(t, x)|$  of  $w(t, \cdot)$ .

This leads to sup-norm bounds for  $v(t, \cdot) = Kw(t, \cdot)$ , but then, instead of a Lipschitz condition, only a **quasi-Lipschitz condition** can be established for  $v$ : There holds

$$\begin{aligned} [v(t, \cdot)]_\ell &= \sup_{\substack{x, y \in \Omega \\ x \neq y}} \frac{|v(t, y) - v(t, x)|}{\ell(|y - x|)} \\ &\leq c \cdot \sup_{x \in \Omega} |w(t, x)| \end{aligned} \quad (5)$$

with

$$\ell(r) = \begin{cases} 0, & r = 0, \\ -r \ln r, & r \in (0, e^{-1}), \\ r, & r \geq e^{-1} \end{cases} \quad (6)$$

the constant  $c$  being independent of  $w$ , [17, Theorem 1.4].

The basic description of the transport of vorticity  $w = \text{rot } v$  is given by the initial value problem of Helmholtz's equation

$$\frac{\partial}{\partial t} w + v \cdot \nabla w = w \cdot \nabla v, \quad 0 \leq t, \quad x \in \bar{\Omega} \quad (7)$$

$$w(0, \cdot) = w_0, \quad t = 0, \quad x \in \bar{\Omega}, \quad (8)$$

which formally follows by taking "rot" in Euler's hydrodynamical equation (in the case of outer forces having a potential). In a 2-dimensional flow parallel to the  $(x, y)$ -plane, the right hand side in (7) becoming

zero, a maximum principle holds for  $w$ , or, if the prescribed outer force does not have a potential, at least an upper bound for  $|w(t, \cdot)|_0$  would be available.

In this way, decisively using quasi-Lipschitz bounds, Kato [6], Hölder [5], Wolibner [27], Yudowich [28] have proved global existence of unique classical solutions to Euler's equation in 2 space dimensions. For the many approaches to this open problem in 3 space dimensions consult [11], [12], [3] and the citations there.

In view of the well-known difficulties of 3-dimensional flows, it seems to be remarkable that a partial discretization in Helmholtz's vorticity transport equation (7) leads to initial value problems allowing unique classical solutions on each bounded interval of time.

## 2 Helmholtz's vorticity transport equation with partial discretization

In the following we consider domains  $\Omega \subset \mathbb{R}^3$  which have the topological type of a ball  $\mathcal{B}$  with  $m$  solid handles,  $m \geq 0$ , inside of  $\mathcal{B}$  a number  $h$  of smaller balls  $\Omega_k$  being cut out. Such a domain is characterized (a) by the presence of a homotopy basis of  $m$  simply closed smooth curves  $l_i \subset \Omega$  which inside  $\Omega$  neither can be continuously deformed into each other nor into a single point, and (b) by the fact that making  $m$  cuts along smooth surfaces  $\Sigma_i \subset \bar{\Omega}$  we can transform the domain  $\Omega$  into a simply connected one. In each such  $m + 1$ -times connected domain  $\Omega$  with  $C^{2+\alpha}$ -boundary  $\partial\Omega = S$  there exist precisely  $m$  linearly independent "Neumann vector fields"  $u_i \in C^{1+\alpha}(\bar{\Omega})$  satisfying the conditions

$$\begin{aligned} \operatorname{rot} u_i &= 0, & \operatorname{div} u_i &= 0 & \text{in } \Omega, \\ u_i \cdot N &= 0 & & & \text{on } S, \end{aligned}$$

$u_i$  having the fluxes

$$\int_{\Sigma_k} u_i \cdot N \, ds = \delta_{ik}$$

across  $\Sigma_k$ , or the circulations

$$\int_{l_k} u_i \cdot dl = \delta_{ik},$$

$i, k = 1, \dots, m$ , respectively. Here  $N(x)$  denotes a unit normal vector in  $x \in \Sigma_k$ ,  $l = l(x)$  a tangential vector of  $l_k$  with any prescribed orientation, see [7, 9, 10, 24]. In [17], Theorem 6.2, Remark 3.5 we have

proved that the map  $K$  from (1) - (3) can be extended to a bounded linear operator

$$\tilde{K} : C^0(\bar{\Omega}) \rightarrow V, \tag{9}$$

where the subspace

$$V = \{u \in C^0(\bar{\Omega}) \mid [u]_\ell < \infty, u \cdot N|_S = 0\}$$

of  $C^0(\bar{\Omega})$  is equipped with the norm  $|u|_\ell = |u|_0 + [u]_\ell$ ,  $[u]_\ell$  denoting the quasi-Lipschitz bound from (5). Here the compatibility conditions (4) and  $\operatorname{div} w = 0$  are unnecessary since we do not require  $w = \operatorname{rot} \tilde{K}w$ .

In [17] the boundedness property of  $\tilde{K}$  has given us the decisive tool for proving

**Theorem 2.1.** *Let the prescribed initial value  $w_0$  be one times continuously differentiable, the vector function  $Z(x) = x + \varepsilon w_0(x)$  for  $x \in \bar{\Omega}$  taking its values in  $\bar{\Omega}$ , where  $\varepsilon \neq 0$  denotes a constant. Then the initial value problem*

$$\begin{aligned} \frac{\partial}{\partial t} w + v \cdot \nabla w &= \frac{1}{\varepsilon} \left\{ v(t, x + \varepsilon w(t, x)) \right. \\ &\quad \left. - v(t, x) \right\}, & (t, x) &\in J \times \bar{\Omega}, \end{aligned} \tag{10}$$

$$w(0, x) = w_0(x) \tag{11}$$

with  $v = \tilde{K}w$  (the function  $v$  being somehow continuously extended to  $J \times \mathbb{R}^3$ ) has a unique global solution  $w \in C^1(J \times \bar{\Omega})$ . The function  $w$  can be approximated by iteration of a contracting map  $T$  and depends continuously on  $w_0$ .

The construction of the map  $T$  is similar as in [15], where the Cauchy problem of (10) in  $\mathbb{R}^3$  without the boundary condition for the velocity field  $v$  has been solved, the initial value  $w_0$  having compact support. The fulfilling of (2) requires the new potential theoretic tools developed in [17].

## 3 Some ideas of the proof (c.p. [18])

For any continuous  $v \in C^0(J \times \bar{\Omega})$ , the boundary condition (2)  $v \cdot N = 0$  on  $S$  ensures global existence for all  $t \in J$  of solutions  $x(t)$  to the initial value problem

$$\frac{d}{dt} x = v(t, x), \quad x(s) = x_s \in \bar{\Omega} \tag{12}$$

starting at  $x_s \in \bar{\Omega}$  at time  $s \in J$ , [14]. The quasi-Lipschitz condition being a special uniqueness condition [13, 25], for any  $v \in C^0(J \times \bar{\Omega})$  which fulfills (2) and  $[v(t, \cdot)]_\ell \leq c$  uniformly, the global flow

$$x = X(t, s, x_s) = (Lv)(t, s, x_s) \tag{13}$$

of (12) is uniquely defined for  $(t, s, x_s) \in J \times J \times \bar{\Omega}$ ,  $X$  describing the unique particles' paths  $x(t) = X(t, s, x_s)$  from (12). For all  $t, s \in J$ ,  $X(t, s, \cdot)$  represents a topological map of  $\bar{\Omega}$  onto itself,  $X$  fulfilling  $X^{-1}(t, s, \cdot) = X(s, t, \cdot)$ ,  $X(s, s, x) = x$ , [2].

Firstly let  $v \in C^0(J \times \bar{\Omega})$  be given,  $v$  being continuously differentiable with respect to  $x \in \bar{\Omega}$  and fulfilling (2). Introducing the Lagrangean representation  $\hat{w}(t, x_0) = w(t, X(t, 0, x_0))$ , from the identity

$$\left(\frac{\partial}{\partial t} \hat{w}(t, \cdot)\right) \circ X^{-1}(t, 0, x) = \frac{\partial}{\partial t} w + v \cdot \nabla w \quad (14)$$

for the material derivative we easily see that the partially discretized Helmholtz equation (10) is equivalent to Cauchy's discretized vorticity equation

$$w(t, x) = \frac{1}{\varepsilon} \{X(t, 0, Z(\cdot)) - X(t, 0, \cdot)\} \circ X(0, t, x) = (HX)(t, x), \quad (15)$$

where  $Z(x) = x + \varepsilon w_0(x) \in \bar{\Omega}$ , and that  $x + \varepsilon w(t, x) \in \bar{\Omega}$  holds for all  $x \in \bar{\Omega}, t \in J$ . Recalling the representations  $X = Lv, v = \tilde{K}w$ , from (15) we are led to the fixed-point equation

$$w = HL\tilde{K}w \equiv Tw. \quad (16)$$

The existence of a unique solution  $w$  depending continuously on  $w_0$  follows by the contracting mapping principle which we apply on  $T$  in the space

$$C_{w_0} = \left\{ f \in C^0(J \times \bar{\Omega}); |f|_0 \leq \frac{\text{diam } \Omega}{|\varepsilon|}, [f(t, \cdot)]_\alpha \leq M_1, f(0, \cdot) = w_0 \right\} \quad (17)$$

with suitable values  $M_1, \alpha$  depending on  $|\varepsilon|, |w_0|_0, |\nabla w_0|_0$  and the length of  $J$ .

Then from the regularization properties of the maps  $\tilde{K}$  and  $L$  we find that the solution  $w = (Tw) \in C_{w_0}$  is one times continuously differentiable with respect to  $t$  and  $x$ , see [18].

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