# Some Numerical Methods of Rational Characterization in Causal Time Series Models 

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#### Abstract

The systematic study of data to obtain specific properties from long (or short) data series is a main objective. The use of rational models and related numerical methods can be useful to predict the behaviour of relevant economic variables. This paper is a continuation of González-Gil [16] which is concerned with illustrating the application of several numerical methods, among them, the corner method, epsilon-algorithm, rs-algorithm and qd-algorithm to time series modelling. These methods which are closely related to theoretical research in Padé Approximation have been proposed to identify some type of rational structure associated to economic data in different contexts (financial, marketing, farming...). Now, we present the study of the statistical significance for the four mentioned methods. Two examples will be considered, namely, a simulated ARMA model and a Transfer Function Model for the sales series M given in Box-Jenkins [7] and Tsay [27].


Key-Words: Padé Approximation, economics, numerical methods, time series modelling.

## 1 Introduction

Over the last two decades, several research activities have helped to obtain new procedures and techniques to characterize dynamic relations associated to data series.
In the context of time series analysis, several authors (Lii [18], Claverie et al. [9], Berlinet-Francq [5]...) have considered the rational theory of series in econometric modelling. From this perspective, several techniques closely related to Padé Approximation (PA) have been proposed to identify possible rational structures associated to chronological data. As the covariance structure of underlying processes exhibits features connected with the order of models, it is possible to use numerical algorithms (corner method, epsilonalgorithm, rs-algorithm and qd-algorithm) linked with Hankel and determinants to estimate the unknown orders from available observations.
The contribution of this paper is the study of the statistical significance of two of these numerical methods, that is, the rs-algorithm and qd-algorithm as a continuation of the work made in González-Gil [16].
Consideration is given to both the univariate and the multivariate multivariate cases.
In the univariate case, the identification of ARMA models has been extensively considered in the last two decades (Beguin et al [2], Mareschal-Mélard [21], Claverie et al [9], Berlinet-Francq [5]).
As for the multivariate case, some results have been given to identify a VARMA model (Tiao-Tsay [26], Reinsel [24], Lütkepohl-Poskitt [20], Pestano-González [22], Berlinet-Francq [6]...) and, as a particular case, a Transfer-Function (TF) model (Liu-Hanssens [19], Lii [18], González et al [15]...).

Next, we show the theoretic characterization of these techniques in a TF model with one output and one or multiple inputs in a causal way.
The empirical work is carried out in the context of the Box-Jenkins's [7] guidelines. Both proposals are illustrated in both univariate and multivariate cases, considering a simulated ARMA model and a TransferFunction Model for the sales series M given in BoxJenkins [7] and Tsay [27].

## 2 The Univariate Case: Some Methods of Rational Characterization in ARMA Models

Let us consider a minimal stationary and invertible Autoregressive Moving Average (ARMA) model of order ( $\mathrm{p}, \mathrm{q}$ ) defined as

$$
\Phi_{\mathrm{p}}(\mathrm{~L}) \mathrm{X}_{\mathrm{t}}=\Theta_{\mathrm{q}}(\mathrm{~L}) \mathrm{a}_{\mathrm{t}}, \quad \forall \mathrm{t} \in \mathrm{Z}
$$

where L is the backward-shift operator, that is, $\mathrm{L}^{\mathrm{m}} \mathrm{X}_{\mathrm{t}}=\mathrm{X}_{\mathrm{t}-\mathrm{m}}, \forall \mathrm{t} \in \mathrm{Z}, \quad \Phi_{\mathrm{p}}(\mathrm{L}), \quad \Theta_{\mathrm{q}}(\mathrm{L})$ are polynomials of degree $p$ and $q$ respectively and $\left\{a_{t} ; t=0, \pm 1, \pm 2, \ldots\right\}$ is a sequence of independently and identically distributed random variables with mean zero and variance $\sigma^{2}$. It is assumed that $\Phi_{\mathrm{p}}(\mathrm{L})$ and $\Theta_{\mathrm{q}}(\mathrm{L})$ have no common factors. Various methods related to PA have been proposed to identify the orders p and q . For instance, the $C$-Table method (Baker-Graves-Morris [1]) from its properties it can be obtained the corner method in econometric literature (Beguin et al [2]). Many later papers have also considered the corner method in ARMA modelling, trying to get to the maximum of their power (MareschalMélard [21]). Also, Beguin et al [2] studied the statistical significance of the C-table. Later, Tsay [27]
and Lii [18] proposed to consider an estimator of the asymptotic variance in terms of the partial derivatives of the entries in the C-table.
The relation of this method with the Hankel determinants and PA has stimulated the study of other algorithms in ARMA models. For instance, we can mention the epsilon-algorithm (Wynn [28]), proposed by Berlinet [3]. Its relation with PA and the corner method can be seen in Brezinski [8] and the characterization for an ARMA process in Berlinet-Francq [5]. They proposed statistical properties of the entries in the epsilon-algorithm, based on the same statistical and assumptions than Beguin et al [2].
We can also refer to the rs-algorithm (Pye-Atchison [23]), proposed by Gray et al. [17] for ARMA models and whose relation with PA can be seen in Brezinski [8]. This algorithm which is linked to determinants of the Hankel matrices associated with the sequence of autocorrelations of $X_{t}, \quad \rho \equiv\left\{\rho_{i}\right\}_{-\infty}^{\infty}$, that is, $C_{i, j}(\rho)=\operatorname{det}\left(\rho_{i-h+k}\right)_{h, k=1}^{j}$, is defined as
$\forall \mathrm{n} \in \mathrm{Z}, \quad \mathrm{s}_{0}^{\mathrm{n}}(\rho)=1, \quad \mathrm{r}_{1}^{\mathrm{n}}(\rho)=\rho_{\mathrm{n}}$
$\forall \mathrm{k} \in \mathrm{N}, \forall \mathrm{n} \in \mathrm{Z}, \quad \mathrm{s}_{\mathrm{k}}^{\mathrm{n}}(\rho)=\mathrm{s}_{\mathrm{k}-1}^{\mathrm{n}+1}(\rho)\left(\left(\mathrm{r}_{\mathrm{k}}^{\mathrm{n}}(\rho)\right)^{-1} \mathrm{r}_{\mathrm{k}}^{\mathrm{n}+1}(\rho)-1\right)$

$$
r_{k+1}^{\mathrm{n}}(\rho)=\mathrm{r}_{\mathrm{k}}^{\mathrm{n}+1}(\rho)\left(\left(\mathrm{s}_{\mathrm{k}}^{\mathrm{n}}(\rho)\right)^{-1} \mathrm{~s}_{\mathrm{k}}^{\mathrm{n}+1}(\rho)-1\right)
$$

It can be proved that

$$
\begin{aligned}
\forall k \in N, \forall n \in Z, \quad \mathrm{r}_{k}^{n}(\rho) & =-\frac{C_{n+k-1, k}(\rho)}{{ }_{1} C_{n+k-2, k-1}(\rho)}, \\
\mathrm{s}_{k}^{n}(\rho) & =\frac{{ }_{1} C_{n+k-1, k}(\rho)}{C_{n+k-1, k}(\rho)}
\end{aligned}
$$

where ${ }_{1} \mathrm{C}_{\mathrm{ij}}(\rho)$ is the determinant of the Hankel matrix associated with $L \rho$, and it is deduced that

$$
r_{j}^{i-j+1}=0 \Leftrightarrow C_{i, j}=0
$$

The study of the statistical significance of the algorithm is given in González [11] computing the values of the $t-$
Student $\frac{s_{k}^{n}(\rho)}{\sqrt{v\left(s_{k}^{n}(\rho)\right)}} \quad$ (respectively, $\frac{r_{k}^{n}(\rho)}{\sqrt{v\left(r_{k}^{n}(\rho)\right)}}$ ) where $v\left(s_{k}^{n}(\rho)\right)$ (respectively $\left.v\left(r_{k}^{n}(\rho)\right)\right)$ represents the variance estimated. Following Tsay [27] and Berlinet [4], the last one can be approximately be represented by

$$
\begin{gathered}
v\left(s_{k}^{n}(\rho)\right) \cong F_{k}^{n^{\prime}}(\rho) M_{k}^{n}(\rho) F_{k}^{n}(\rho) \text { (respectively } \\
v\left(r_{k}^{n}(\rho)\right) \cong F_{k}^{n^{\prime}}(\rho) M_{k}^{n}(\rho) F_{k}^{n}(\rho)
\end{gathered}
$$

where $\mathrm{M}_{\mathrm{k}}^{\mathrm{n}}(\rho)$ is the sample covariance matrix for the sequence $\left(\rho_{n}, \ldots, \rho_{k+n}\right)$, that is,

$$
\begin{aligned}
& M_{k}^{\mathrm{n}}(\rho)=\left(\mathrm{m}_{\mathrm{ij}}^{\mathrm{k}, \mathrm{n}}\right)_{\mathrm{i}, \mathrm{j}=1, \ldots, \mathrm{k}+1} / \mathrm{m}_{\mathrm{ii}}^{\mathrm{k}, \mathrm{n}}=\mathrm{v}\left(\rho_{\mathrm{k}+\mathrm{i}-1}\right), \mathrm{m}_{\mathrm{ij}}^{\mathrm{k}, \mathrm{n}}= \\
& =\operatorname{cov}\left(\rho_{\mathrm{n}+\mathrm{i}-1}, \rho_{\mathrm{n}+\mathrm{j}-1}\right)
\end{aligned}
$$

and $\mathrm{F}_{\mathrm{k}}^{\mathrm{n}}(\rho)$ is the sequence $\left({ }^{n} s_{k}^{n}(\rho), \ldots,{ }^{n+k} s_{k}^{n}(\rho)\right)$ (respectively, $\left({ }^{n} r_{k}^{n}(\rho), \ldots,{ }^{n+k} r_{k}^{n}(\rho)\right)$ ) where

$$
\begin{aligned}
& { }^{\mathrm{i}} \mathrm{~S}_{\mathrm{k}}^{\mathrm{n}}(\rho) \equiv \frac{\partial \mathrm{s}_{\mathrm{k}}^{\mathrm{n}}}{\partial \rho_{\mathrm{i}}}(\rho)= \\
& { }^{i} s_{k-1}^{n+1}(\rho) \frac{r_{k}^{n}(\rho)^{i} r_{k}^{n+1}(\rho)-r_{k}^{n+1}(\rho)^{i} r_{k}^{n}(\rho)}{\left(r_{k}^{n}(\rho)\right)^{2}}+{ }^{i} s_{k-1}^{n+1}(\rho)\left(\frac{r_{k}^{n+1}(\rho)}{r_{k}^{n}(\rho)}-1\right), \\
& \text { if } \mathrm{i}=\mathrm{n}, \mathrm{n}+1, \ldots, \mathrm{n}+\mathrm{k} \text { and } 0 \text {, otherwise } \\
& { }^{\mathrm{i}} \mathrm{r}_{\mathrm{k}+1}^{\mathrm{n}}(\rho) \equiv \frac{\partial \mathrm{r}_{\mathrm{k}+1}^{\mathrm{n}}}{\partial \rho_{\mathrm{i}}}(\rho)= \\
& { }^{i} r_{k}^{n}(\rho) \frac{s_{k-1}^{n}(\rho)^{i} s_{k-1}^{n+1}(\rho)-s_{k-1}^{n+1}(\rho)^{i} s_{k-1}^{n}(\rho)}{\left(s_{k-1}^{n}(\rho)\right)^{2}}+r_{k}^{i}{ }^{n+1}(\rho)\left(\frac{s_{k-1}^{n+1}(\rho)}{s_{k-1}^{n}(\rho)}-1\right)
\end{aligned}
$$

if $\mathrm{i}=\mathrm{n}, \mathrm{n}+1, \ldots, \mathrm{n}+\mathrm{k}$ and 0 , otherwise
where $\quad{ }^{\mathrm{i}} \mathrm{s}_{0}^{\mathrm{n}}(\rho)=0$ and $\quad{ }^{\mathrm{i}} \mathrm{r}_{1}^{\mathrm{n}}(\rho)=\left\{\begin{array}{ll}1 & \mathrm{i}=\mathrm{n} \\ 0 & \mathrm{i} \neq \mathrm{n}\end{array} \quad(\forall \mathrm{n}, \mathrm{i} \geq 0)\right.$ are the initial values.
With regard to the qd-algorithm (Rutishaüser [25]), it has been considered by Berlinet [3] to study the partial autocorrelation function in an ARMA model and by González [11] and González and Gil [16] to model identification. This algorithm is defined as

$$
\begin{aligned}
& \forall \mathrm{n} \in \mathrm{Z}, \quad \mathrm{~d}_{0}^{\mathrm{n}}(\rho)=0, \quad \mathrm{q}_{1}^{\mathrm{n}}(\rho)=\frac{\rho_{\mathrm{n}+1}}{\rho_{\mathrm{n}}} \\
& \forall \mathrm{k} \in \mathrm{~N}, \forall \mathrm{n} \in \mathrm{Z}, \quad \mathrm{~d}_{\mathrm{k}}^{\mathrm{n}}(\rho)=\mathrm{q}_{\mathrm{k}}^{\mathrm{n}+1}(\rho)-\mathrm{q}_{\mathrm{k}}^{\mathrm{n}}(\rho)+\mathrm{d}_{\mathrm{k}-1}^{\mathrm{n}+1}(\rho) \\
& \\
& \mathrm{q}_{\mathrm{k}+1}^{\mathrm{n}}(\rho)=\frac{\mathrm{d}_{\mathrm{k}}^{\mathrm{n}+1}(\rho) \mathrm{q}_{\mathrm{k}}^{\mathrm{n}+1}(\rho)}{\mathrm{d}_{\mathrm{k}}^{\mathrm{n}}(\rho)}
\end{aligned}
$$

Its relation with the PA is not direct (Brezinski [8]) and it can be proved that

$$
\begin{aligned}
& \forall \mathrm{k} \in \mathrm{~N}, \forall \mathrm{n} \in \mathrm{Z}, \\
& \mathrm{q}_{\mathrm{k}}^{\mathrm{n}}(\rho)=\frac{\mathrm{C}_{\mathrm{n}+\mathrm{k}, \mathrm{k}}(\rho) \mathrm{C}_{\mathrm{n}+\mathrm{k}-2, \mathrm{k}-1}(\rho)}{\mathrm{C}_{\mathrm{n}+\mathrm{k}-1, \mathrm{k}}(\rho) \mathrm{C}_{\mathrm{n}+\mathrm{k}-1, \mathrm{k}-1}(\rho)}, \\
& \mathrm{d}_{\mathrm{k}}^{\mathrm{n}}(\rho)=\frac{\mathrm{C}_{\mathrm{n}+\mathrm{k}-1, \mathrm{k}-1}(\rho) \mathrm{C}_{\mathrm{n}+\mathrm{k}, \mathrm{k}+1}(\rho)}{\mathrm{C}_{\mathrm{n}+\mathrm{k}-1, \mathrm{k}}(\rho) \mathrm{C}_{\mathrm{n}+\mathrm{k}, \mathrm{k}}(\rho)}
\end{aligned}
$$

It is deduced that

$$
\begin{aligned}
& C_{i-2, j-1}(\rho) \neq 0, C_{i-1, j}(\rho) \neq 0, C_{i-1, j-1}(\rho) \neq 0 \\
& C_{i, j}(\rho)=0 \Rightarrow q_{j}^{i-j}(\rho)=0 \\
& C_{i-1, j-2}(\rho) \neq 0, C_{i-1, j-1}(\rho) \neq 0, C_{i, j-1}(\rho) \neq 0 \\
& C_{i, j}(\rho)=0 \Rightarrow d_{j-1}^{i-j+1}(\rho)=0
\end{aligned}
$$

In order to study the statistical significance for the elements of the qd-algorithm, the same statistical and similar notations are used. Partial derivatives are computed following the next iterative procedure

$$
\begin{gathered}
{ }^{\mathrm{i}} \mathrm{~d}_{0}^{\mathrm{n}}(\rho)=0, \forall \mathrm{n}, \mathrm{i} \geq 0 \\
{ }^{\mathrm{i}} \mathrm{q}_{1}^{\mathrm{n}}(\rho)=\left\{\begin{array}{cc}
-\frac{\mathrm{r}_{\mathrm{n}+1}}{\left(\mathrm{r}_{\mathrm{n}}\right)^{2}} & \mathrm{i}=\mathrm{n} \\
\frac{1}{\mathrm{r}_{\mathrm{n}}} & \mathrm{i}=\mathrm{n}+1 \\
0 & \mathrm{i} \neq \mathrm{n}, \mathrm{n}+1
\end{array}\right.
\end{gathered}
$$

For $\mathrm{k}>0$ :
${ }^{\mathrm{i}} \mathrm{q}_{\mathrm{k}+1}^{\mathrm{n}}(\rho) \equiv \frac{\partial \mathrm{q}_{\mathrm{k}+1}^{\mathrm{n}}}{\partial \mathrm{p}_{\mathrm{i}}}(\rho)=$
$\frac{\left(d_{k}^{n}(\rho)^{i} d_{k}^{n+1}(\rho)-d_{k}^{n+1}(\rho)^{i} d_{k}^{n}(\rho)\right) q_{k}^{n+1}(\rho)+d_{k}^{n}(\rho) d_{k}^{n+1}(\rho)^{i} q_{k}^{n+1}(\rho)}{\left(d_{k}^{n}(\rho)\right)^{2}}$
if $\mathrm{i}=\mathrm{n}, \mathrm{n}+1, \ldots, \mathrm{n}+\mathrm{k}+1$ and 0 , otherwise
${ }^{\mathrm{i}} \mathrm{d}_{\mathrm{k}}^{\mathrm{n}}(\rho) \equiv \frac{\partial \mathrm{d}_{\mathrm{k}}^{\mathrm{n}}}{\partial \rho_{\mathrm{i}}}(\rho)={ }^{\mathrm{i}} \mathrm{q}_{\mathrm{k}}^{\mathrm{n}+1}(\rho)-{ }^{\mathrm{i}} \mathrm{q}_{\mathrm{k}}^{\mathrm{n}}(\rho)+{ }^{\mathrm{i}} \mathrm{d}_{\mathrm{k}-1}^{\mathrm{n}+1}(\rho)$
if $\mathrm{i}=\mathrm{n}, \mathrm{n}+1, \ldots, \mathrm{n}+\mathrm{k}+1$ and 0 , otherwise
These methods can be used to find a parsimonious approximation or reduce possible competing models to only a few for further testing. Other techniques can be found, for example, in Berlinet-Francq [5].
This proposal is illustrated following the model $\mathrm{X}_{\mathrm{t}}-0.7 \mathrm{X}_{\mathrm{t}-1}=\mathrm{a}_{\mathrm{t}}+0.5 \mathrm{a}_{\mathrm{t}-1}, \quad \forall \mathrm{t} \in \mathrm{Z} \quad$ simulated $\quad$ by Berlinet-Francq [5], where $a_{t}$ is a white noise process with media zero and variance 1. Initial values were taken equal to zero; 200 values were generated but only the last 100 values were considered.
Using the rs-algorithm, the obtained results are

| Critical Value | Accepted (p,q) models |
| :---: | :---: |
| 1.28 | $(1,5)(2,1)$ |
| 1.64 | $(1,1)$ |
| 1.96 | $(1,1)$ |
| 2.33 | $(1,1)$ |
| 2.58 | $(1,1)$ |
| 2.81 | $(1,1)$ |
| 3.09 | $(1,1)$ |
| 3.29 | $(1,1)$ |
| 3.72 | $(1,1)$ |
| 4.26 | $(1,1)$ |

Using the qd-algorithm, results are given below:

| Critical Value | Accepted (p,q) <br> Models |
| :---: | :---: |
| 1.28 | $(1,1)$ |
| 1.64 | $(1,1)$ |
| 1.96 | $(1,1)$ |
| 2.33 | $(1,1)$ |
| 2.58 | $(1,1)(0,2)$ |
| 2.81 | $(1,1)(0,2)$ |
| 3.09 | $(1,1)(0,2)$ |
| 3.29 | $(1,1)(0,2)$ |
| 3.72 | $(1,1)(0,2)$ |
| 4.26 | $(1,1)(0,2)$ |

Obtained results suggest that both methods are efficient alternatives to reproduce the simulated model.

## 3 The Multivariate Case: Some Methods of Rational Characterization in Causal TF Models

Let us consider a VARMA $(p, q)$ process defined as $\Phi_{\mathrm{p}}(\mathrm{L}) \mathrm{Z}_{\mathrm{t}}=\Theta_{\mathrm{q}}(\mathrm{L}) \mathrm{u}_{\mathrm{t}}$
where now $\Phi_{p}(\mathrm{~L})$ and $\Theta_{q}(\mathrm{~L})$ are matrix polynomials of dimension n and degrees p and q respectively, $\mathrm{Z}_{\mathrm{t}}$ is a multiple process $Z_{t}$ and $u_{t}$ a vector of independent white noise processes. A structure of particular interest when

$$
Z_{t}=\binom{X_{t}}{Y_{t}}, \Phi_{p}=\left(\begin{array}{cc}
\varphi & 0 \\
\psi & \phi
\end{array}\right), \Theta_{q}=\left(\begin{array}{cc}
\alpha & 0 \\
0 & \theta
\end{array}\right), u_{t}=\binom{c_{t}}{a_{t}}
$$

can be expressed as

$$
\begin{aligned}
& \varphi(\mathrm{L}) \mathrm{X}_{\mathrm{t}}=\alpha(\mathrm{L}) \mathrm{c}_{\mathrm{t}} \\
& \phi(\mathrm{~L}) \mathrm{Y}_{\mathrm{t}}+\psi(\mathrm{L}) \mathrm{X}_{\mathrm{t}}=\theta(\mathrm{L}) \mathrm{a}_{\mathrm{t}}, \quad \forall \mathrm{t} \in \mathrm{Z}
\end{aligned}
$$

If $\phi$ is invertible, $\mathrm{Y}_{\mathrm{t}}$ is given by

$$
\mathrm{Y}_{\mathrm{t}}=-\phi^{-1}(\mathrm{~L}) \psi(\mathrm{L}) \mathrm{X}_{\mathrm{t}}+\mathrm{N}_{\mathrm{t}}, \quad \forall \mathrm{t} \in \mathrm{Z}
$$

In this expression, which is called the TF model, the output $\mathrm{Y}_{\mathrm{t}}$ is a function of the contemporary and delayed effects of the input variable $X_{t}$. It is assumed a one-way causal relation $X_{t} \rightarrow Y_{t}$ and the presence of a disturbance series described as $\mathrm{N}_{\mathrm{t}}=\phi^{-1}(\mathrm{~L}) \theta(\mathrm{L}) \mathrm{a}_{\mathrm{t}}$.
Here we refer to TF models with one output $\mathrm{Y}_{\mathrm{t}} \equiv \mathrm{y}_{\mathrm{t}}$ and one or multiple inputs $X_{t} \equiv\left(X_{i t}\right)_{i=1, \ldots, n}$, that is,

$$
\mathrm{y}_{\mathrm{t}}=\sum_{\mathrm{i}=1}^{\mathrm{n}} \frac{\omega_{\mathrm{is}_{\mathrm{i}}}(\mathrm{~L})}{\delta_{\mathrm{iri}_{\mathrm{i}}}(\mathrm{~L})} \mathrm{L}^{\mathrm{b}_{\mathrm{i}}} \mathrm{x}_{\mathrm{it}}+\mathrm{N}_{\mathrm{t}}
$$

where $\quad \omega_{i s_{i}}(\mathrm{~L})=\omega_{\mathrm{i} 0}+\omega_{\mathrm{i} 1} \mathrm{~L}+\ldots+\omega_{\mathrm{is}_{\mathrm{i}}} \mathrm{L}^{\mathrm{s}_{\mathrm{i}}} \quad$ and $\delta_{\mathrm{ir}_{\mathrm{i}}}(\mathrm{L})=\delta_{\mathrm{i} 0}+\delta_{\mathrm{i} 1} \mathrm{~L}+\ldots+\delta_{\mathrm{ir}_{\mathrm{i}}} \mathrm{L}^{\mathrm{r}_{\mathrm{i}}}$, $\mathrm{b}_{\mathrm{i}}$ is the delay in the response of $y_{t}$ to $x_{i t}$ and $a_{t}$ is a white noise process.
The Box-Jenkins's guideline deals with modelling this type of input-output dynamic relations. It is based on the specification of the dynamic structures in a TF model from the sample available information.
In order to identify the values of $b_{i}, s_{i}$ and $r_{i}$ and obtain $a$ satisfactory response of $\mathrm{y}_{\mathrm{t}}$ for each input, several proposals have been considered, just based on algorithms related to the PA. Padé table computation offers consistent initial values, without previous identification of the noise structure.
We can write the following compact relation

$$
\mathrm{y}_{\mathrm{t}}=\sum_{\mathrm{i}=1}^{\mathrm{n}} \mathrm{v}_{\mathrm{i}}(\mathrm{~L}) \mathrm{x}_{\mathrm{it}}+\mathrm{N}_{\mathrm{t}} ; \quad \mathrm{v}_{\mathrm{i}}(\mathrm{~L})=\sum_{\mathrm{i}=0}^{\infty} \mathrm{v}_{\mathrm{ij}} \mathrm{~L}^{\mathrm{j}}
$$

where $\mathrm{v}_{\mathrm{i}}(\mathrm{L})$ is the Impulse Response Function (IRF), which transforms $x_{i t}$ into $y_{t}$.
First, the weights $\mathrm{v}_{\mathrm{ij}}$ for each input and the matrix covariance are computed using Ordinary Least Squares or maximising the Likelihood Function in accordance with the following expression

$$
\mathrm{y}_{\mathrm{t}} \cong \sum_{\mathrm{i}=1}^{\mathrm{n}} \sum_{\mathrm{j}=0}^{\mathrm{k}_{\mathrm{i}}} \hat{\mathrm{v}}_{\mathrm{ij}} \mathrm{~L}^{\mathrm{j}} \mathrm{x}_{\mathrm{it}}+\mathrm{N}_{\mathrm{t}}^{*}
$$

The lag structure for $\mathrm{x}_{\mathrm{it}}$ is approximated by choosing a finite number $k_{i}$ of terms. $N_{t}^{*}$ is the reestimated noise term.
Next, we define the sequence of estimated relative weights $\hat{\eta}_{i}=\left(\hat{\eta}_{i j}\right)_{j \in N}$ for $\mathrm{x}_{\mathrm{it}}$ as

$$
\hat{\mathrm{v}}_{\mathrm{i}, \max }=\max _{\mathrm{j}}\left|\hat{\mathrm{v}}_{\mathrm{ij}}\right| ; \quad \hat{\eta}_{\mathrm{ij}}=\frac{\hat{\mathrm{v}}_{\mathrm{ij}}}{\hat{\mathrm{v}}_{\mathrm{i}, \max }}
$$

that verifies the following linear difference equation of order $r_{i}$ and rank $b_{i}+s_{i}$
$\eta_{\mathrm{ij}}-\delta_{\mathrm{i} 1} \eta_{\mathrm{i}, \mathrm{j}-1}-\delta_{\mathrm{i} 2} \eta_{\mathrm{i}, \mathrm{j}-2}-\ldots-\delta_{\mathrm{iri}} \eta_{\mathrm{i}, \mathrm{j}-\mathrm{r}_{\mathrm{i}}} \begin{cases}=0 & \mathrm{j}>\mathrm{b}_{\mathrm{i}}+\mathrm{s}_{\mathrm{i}} \\ \neq 0 & \mathrm{j}=b_{i}+s_{\mathrm{i}}\end{cases}$
This expression just constitutes a characterization for a TF model.
Several methods have been proposed for obtaining a identifiable TF model. Among them, the corner method (Liu-Hanssens [19], Tsay [27], Lii [18], Claverie et al [9]...), provides a generalisation of the one given in the univariate case. For this method, the study of the statistical significance can be also found in Tsay [27].
In the context of a TF model with multiple inputs, the epsilon-algorithm has been proposed by González-Cano [12,13] and González et al [14,15]...) The study of the statistical significance can be seen in Berlinet-Francq [5] and González et al [15].
We can also bring out the rs-algorithm, which has been proposed by González [11] and González-Gil [16] for a TF model in accordance with the following result.
Theorem 1.- $\hat{\mathrm{v}}_{\mathrm{i}}(\mathrm{L})$ has a rational representation with orders $\left(\mathrm{b}_{\mathrm{i}}, \mathrm{S}_{\mathrm{i}}, \mathrm{r}_{\mathrm{i}}\right)$ if the following conditions are verified:
a) $\left\{\begin{array}{l}\mathrm{s}_{\mathrm{r}_{\mathrm{i}}}^{\mathrm{k} \mathrm{r}_{\mathrm{i}}}\left(\hat{\eta}_{\mathrm{i}}\right)=\mathrm{C}_{1}, \quad \forall \mathrm{k}>\mathrm{b}_{\mathrm{i}}+\mathrm{s}_{\mathrm{i}} \\ \mathrm{s}_{\mathrm{r}_{\mathrm{i}}}^{\mathrm{b}_{\mathrm{i}}+\mathrm{r}_{\mathrm{i}}}\left(\hat{\eta}_{\mathrm{i}}\right) \neq \mathrm{C}_{1}\end{array}\right.$
b) $\left\{\begin{array}{ll}r_{j+1}^{k+j+1}\left(\hat{\eta}_{i}\right)=0, & \forall \mathrm{j}, \\ \mathrm{r}_{\mathrm{i}} & \forall \mathrm{k}<\mathrm{b}_{\mathrm{i}} \\ \mathrm{r}_{\mathrm{r}_{\mathrm{i}}+1}+\mathrm{r}_{\mathrm{i}}+1\end{array} \hat{\eta}_{\mathrm{i}}\right)=0, \quad \forall \mathrm{k}>\mathrm{b}_{\mathrm{i}}+\mathrm{s}_{\mathrm{i}}$

Displaying these values in a double-entry table, tabular structures for each input $\mathrm{x}_{\mathrm{it}}$ can be obtained (GonzálezGil [16]).
In certain cases, some transformations in the sequence of relative weights could be necessary to avoid computational instability.
In the same way, the qd-algorithm has been proposed by González [11] and González-Gil [16] to identify a TF model in accordance with the following characterization. Theorem 2.- If $\hat{\mathrm{v}}_{\mathrm{i}}(\mathrm{L})$ has a rational representation with orders $\left(b_{i}, s_{i}, r_{i}\right)$, then one of the following statements is verified:
a) $\left\{\begin{array}{l}q_{j}^{k-j}\left(\hat{\eta}_{i}\right)=0, \quad \forall j, \forall k<b_{i} \\ q_{j}^{k-j}\left(\hat{\eta}_{i}\right)=0, \quad \forall k>b_{i}+s_{i}, j>r_{i} \\ q_{r_{i}}^{k-r_{i}}\left(\hat{\eta}_{i}\right) \neq 0, \quad \forall k \geq b_{i}+s_{i} \\ q_{j}^{b_{i}+s_{i}-j}\left(\hat{\eta}_{i}\right) \neq 0, \quad \forall j \geq r_{i}\end{array}\right.$

Displaying the entries in a double-entry table, tabular structures can be obtained for each input $x_{i t}$ (GonzálezGil [16]). Comments made in section 2 are again valid here to study the statistical significance.
To illustrate these methods a simulated model with two inputs (Liu-Hanssens [19]) is considered,

$$
\begin{gathered}
\mathrm{y}_{\mathrm{t}}=\left(2 \mathrm{~L}^{3}+4 \mathrm{~L}^{4}\right) \mathrm{x}_{1 \mathrm{t}}+\frac{1.5 \mathrm{~L}^{2}+3 \mathrm{~L}^{3}}{1-\mathrm{L}+0.24 \mathrm{~L}^{2}} \mathrm{x}_{2 \mathrm{t}}+\mathrm{N}_{\mathrm{t}}, \mathrm{t}=1, . ., 100 \\
\left(1-1.3 \mathrm{~L}+0.4 \mathrm{~L}^{2}\right) \mathrm{N}_{\mathrm{t}}=\mathrm{a}_{\mathrm{t}}, \quad \mathrm{a}_{\mathrm{t}} \mathrm{~N}(0,2) \\
\left(1-1.4 \mathrm{~L}+0.48 \mathrm{~L}^{2}\right) \mathrm{x}_{1 \mathrm{t}}=\mathrm{c}_{\mathrm{t}}, \quad \mathrm{c}_{\mathrm{t}} \mathrm{~N}(0,1) \\
(1-0.7 \mathrm{~L}) \mathrm{x}_{2 \mathrm{t}}=\mathrm{d}_{\mathrm{t}}, \quad \mathrm{~d}_{\mathrm{t}} \mathrm{~N}(0,2)
\end{gathered}
$$

where $a_{t}$ is independent of $c_{t}$ and $d_{t}$, and $c_{t}$ and $d_{t}$ are contemporaneously correlated with correlation 0.7 .
The identification pattern is clearly $b_{1}=3, s_{1}=1, r_{1}=0$, $\mathrm{b}_{2}=2, \mathrm{~s}_{2}=1$ and $\mathrm{r}_{2}=2$.
Previous results for the corner method and the epsilon algorithm can be seen in Liu-Hanssens [19] and González et al [15] respectively. They don’t differ substantially from the next ones given for the rsalgorithm and the qd-algorithm.
The IRF is now computed by using the Cochrane-Orcutt iterative method, one of the three ones considered in González et al [15]. The other methods and Least Ordinary Squares estimation provide similar results.

Table $r$
Statistical significance for the $\left\{(-1)^{\mathbf{j}} \eta_{1 i}\right\}$

|  | $\mathbf{1}$ | $\mathbf{2}$ | $\mathbf{3}$ | $\mathbf{4}$ | $\mathbf{5}$ | $\mathbf{6}$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $\mathbf{0}$ | .- .132 |  |  |  |  |  |
| $\mathbf{1}$ | .241 | -.006 |  |  |  |  |
| $\mathbf{2}$ | -.176 | -.036 | .002 |  |  |  |
| $\mathbf{3}$ | 1.566 | -.052 | .009 | -.001 |  |  |
| $\mathbf{4}$ | 2.523 | -1.170 | .503 | -.020 | .001 |  |
| $\mathbf{5}$ | 1.265 | -.090 | .001 | .000 | .000 | .000 |
| $\mathbf{6}$ | 1.050 | .004 | -.002 | .000 | .000 | .000 |
| $\mathbf{7}$ | .795 | .062 | -.001 | .000 | .000 |  |
| $\mathbf{8}$ | -.142 | -.046 | .006 | .000 |  |  |
| $\mathbf{9}$ | .626 | -.020 | .000 |  |  |  |
| $\mathbf{1 0}$ | -.123 | -.003 |  |  |  |  |
| $\mathbf{1 1}$ | .081 |  |  |  |  |  |


|  |  |  | ble r |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | stical | gnifi | anc | or | \{( | $\left.)^{\mathrm{j}} \eta_{2 \mathrm{j}}\right\}$ |
|  | 1 | 2 | 3 | 4 | 5 | 6 |
| 0 | -. 215 |  |  |  |  |  |
| 1 | . 212 | -. 010 |  |  |  |  |
| 2 | 1.839 | -. 050 | . 006 |  |  |  |
| 3 | -6.227 | 1.316 | -. 029 | . 006 |  |  |
| 4 | 5.428 | -. 643 | -. 010 | . 000 | . 000 |  |
| 5 | -3.890 | . 124 | -. 013 | . 000 | . 000 | . 000 |
| 6 | 2.378 | . 082 | . 002 | . 000 | . 000 | . 000 |
| 7 | -1.562 | -. 093 | . 001 | . 000 | . 000 |  |
| 8 | 1.480 | -. 167 | . 001 | . 000 |  |  |
| 9 | -. 583 | -. 072 | . 000 |  |  |  |
| 10 | . 897 | -. 056 |  |  |  |  |
| 11 | -. 271 |  |  |  |  |  |

Therefore, among different alternatives it can be obtained the identification pattern of the model.

Table q
Statistical significance for $\left\{(-1)^{\mathrm{j}} \eta_{1 \mathrm{j}}\right\}$

|  | $\mathbf{1}$ | $\mathbf{2}$ | $\mathbf{3}$ | $\mathbf{4}$ | $\mathbf{5}$ | $\mathbf{6}$ |
| :--- | ---: | ---: | ---: | ---: | ---: | ---: |
| $\eta_{\mathbf{0}}=-.051$ |  |  |  |  |  |  |
| $\mathbf{0}$ | -.138 |  |  |  |  |  |
| $\mathbf{1}$ | -.170 | .068 |  |  |  |  |
| $\mathbf{2}$ | -.180 | .254 | .027 |  |  |  |
| $\mathbf{3}$ | 1.205 | -.211 | -.238 | -.031 |  |  |
| $\mathbf{4}$ | 1.035 | -.832 | .421 | .216 | .093 |  |
| $\mathbf{5}$ | .723 | -.203 | -.347 | .295 | .302 | -.276 |
| $\mathbf{6}$ | .572 | .046 | -.055 | .019 | .004 | -.027 |
| $\mathbf{7}$ | -.146 | -.443 | .049 | -.019 | -.025 |  |
| $\mathbf{8}$ | -.148 | .148 | -.475 | -.044 |  |  |
| $\mathbf{9}$ | -.126 | .141 | .024 |  |  |  |
| $\mathbf{1 0}$ | -.078 | -.125 |  |  |  |  |
| $\mathbf{1 1}$ | -.084 |  |  |  |  |  |

Table q
Statistical significance for $\left\{(-1)^{\mathrm{j}} \eta_{2 \mathrm{j}}\right\}$

|  | $\mathbf{1}$ | $\mathbf{2}$ | $\mathbf{3}$ | $\mathbf{4}$ | $\mathbf{5}$ | $\mathbf{6}$ |
| :--- | ---: | ---: | ---: | ---: | ---: | ---: |
| $\eta_{\mathbf{0}}=-.031$ |  |  |  |  |  |  |
| $\mathbf{0}$ | -.128 |  |  |  |  |  |
| $\mathbf{1}$ | .222 | -.215 |  |  |  |  |
| $\mathbf{2}$ | -1.580 | .327 | -.061 |  |  |  |
| $\mathbf{3}$ | -3.380 | -.594 | .262 | .087 |  |  |
| $\mathbf{4}$ | -2.632 | -.265 | .067 | -.089 | 1.302 |  |
| $\mathbf{5}$ | -1.690 | .534 | -.164 | .135 | .075 | -.005 |
| $\mathbf{6}$ | -1.081 | -.064 | .084 | .090 | -.058 | -.006 |
| $\mathbf{7}$ | -.884 | .331 | -.046 | -.058 | .045 |  |
| $\mathbf{8}$ | -.473 | .349 | .124 | .051 |  |  |
| $\mathbf{9}$ | -.412 | 1.112 | .171 |  |  |  |
| $\mathbf{1 0}$ | -.232 | -.123 |  |  |  |  |
| $\mathbf{1 1}$ | -.058 |  |  |  |  |  |

The orders for the first input can be adequately identified. For the second one, a possible pattern is $b_{2}=2$, $\mathrm{s}_{2}=0, \mathrm{r}_{2}=1$.

## 4 An Application

Now we consider empirical results for a set of sales leading indicator data identified as series M in Box-

Jenkins [7] and also studied in Tsay [27]. Data set are 150 pair of observations $\left(\mathrm{x}_{\mathrm{t}}, \mathrm{y}_{\mathrm{t}}\right)$.
The FT model proposed by Box-Jenkins [7] is

$$
\begin{gathered}
\Delta \mathrm{y}_{\mathrm{t}}=0.035+\frac{4.82 \mathrm{~L}^{3}}{1-0.72 \mathrm{~L}} \Delta \mathrm{x}_{\mathrm{t}}+(1-0.54 \mathrm{~L}) \mathrm{a}_{\mathrm{t}} \\
\Delta \mathrm{x}_{\mathrm{t}}=(1-0.32 \mathrm{~L}) \mathrm{b}_{\mathrm{t}}
\end{gathered}
$$

In this specification $\Delta=1-\mathrm{L}$ is the operator that allow to obtain the rates of data variation and $a_{t}$ and $b_{t}$ are white noise processes. Therefore, $\mathrm{b}=3, \mathrm{~s}=0$ and $\mathrm{r}=1$, which confirms the model proposed by Box-Jenkins [7]. Tsay [27] carried out further examination studying the statistical significance of the corner table.
Starting from Berlinet-Francq [5] and Tsay [27], González et al [15] showed the statistical significance of null entries in the epsilon table to confirm the adequacy of the identified model.
In this sense, applying the epsilon-algorithm to the sequence ( -1$)^{i} \eta_{i \text { i. }}$ it can be deduced the following table of statistical significance

|  |  | $\mathbf{0}$ | $\mathbf{2}$ | $\mathbf{4}$ | $\mathbf{6}$ | $\mathbf{8}$ | $\mathbf{1 0}$ |
| :--- | ---: | ---: | ---: | ---: | ---: | ---: | ---: |
| $\mathbf{1 2}$ |  |  |  |  |  |  |  |
| $\mathbf{0}$ | .105 |  |  |  |  |  |  |
| $\mathbf{1}$ | -.105 | -.053 |  |  |  |  |  |
| $\mathbf{2}$ | -.211 | -.109 | .103 |  |  |  |  |
| $\mathbf{3}$ | 10.541 | 6.419 | 5.199 | 4.729 |  |  |  |
| $\mathbf{4}$ | -7.800 | -.046 | .025 | -.010 | -.117 |  |  |
| $\mathbf{5}$ | 5.692 | .025 | .002 | .024 | -.082 | -.066 |  |
| $\mathbf{6}$ | -4.360 | -.011 | .025 | .042 | -.032 | .032 | .058 |
| $\mathbf{7}$ | 3.130 | -.123 | -.083 | -.032 | -.039 | .044 | .051 |
| $\mathbf{8}$ | -2.460 | -.017 | -.074 | .033 | .043 | .025 |  |
| $\mathbf{9}$ | 1.792 | .189 | .173 | .059 | .051 |  |  |
| $\mathbf{1 0}$ | -1.054 | .144 | .162 | .024 |  |  |  |
| $\mathbf{1 1}$ | .843 | -.086 | -.117 |  |  |  |  |
| $\mathbf{1 2}$ | -.843 | -.206 |  |  |  |  |  |
| $\mathbf{1 3}$ | .422 |  |  |  |  |  |  |

With these results, the orders for the accepted models according to certain critical values are as follows

| Critical value | Accepted (b,s,r) models |
| :---: | :---: |
| 1.28 | $(3,6,0)(3,0,1)$ |
| 1.64 | $(3,6,0)(3,0,1)$ |
| 1.96 | $(3,5,0)(3,0,1)$ |
| 2.33 | $(3,5,0)(3,0,1)$ |
| 2.58 | $(3,4,0)(3,0,1)$ |
| 2.81 | $(3,4,0)(3,0,1)$ |
| 3.09 | $(3,4,0)(3,0,1)$ |
| 3.29 | $(3,3,0)(3,0,1)$ |
| 3.72 | $(3,3,0)(3,0,1)$ |
| 4.26 | $(3,3,0)(3,0,1)$ |

They confirm the model proposed by Box-Jenkins [7] and Tsay [27]. Other possible models can be also obtained although they are less parsimonious.
Now, applying the rs-algorithm, next results are obtained

Table r (Statistical significance)

|  | $\mathbf{1}$ | $\mathbf{2}$ | $\mathbf{3}$ | $\mathbf{4}$ | $\mathbf{5}$ | $\mathbf{6}$ |
| :--- | ---: | ---: | ---: | ---: | ---: | ---: |
| $\mathbf{0}$ | -.208 |  |  |  |  |  |
| $\mathbf{1}$ | .122 | -.002 |  |  |  |  |
| $\mathbf{2}$ | .083 | .000 | -.000 |  |  |  |
| $\mathbf{3}$ | -10.998 | .084 | -.001 | .000 |  |  |
| $\mathbf{4}$ | 8.169 | -.410 | .020 | .000 | .000 |  |
| $\mathbf{5}$ | -5.533 | -.176 | .000 | .000 | .000 | .000 |
| $\mathbf{6}$ | 4.239 | -.177 | .002 | .000 | .000 | .000 |
| $\mathbf{7}$ | -2.930 | -.137 | .001 | .000 | .000 |  |
| $\mathbf{8}$ | 2.561 | -.152 | -.000 | .000 |  |  |
| $\mathbf{9}$ | -1.733 | .004 | -.000 |  |  |  |
| $\mathbf{1 0}$ | 1.155 | .037 |  |  |  |  |
| $\mathbf{1 1}$ | -.976 |  |  |  |  |  |

With these results, the orders for the accepted models according to certain critical values are as follows:

| Critical value | Accepted (b,s,r) models |
| :---: | :---: |
| 1.28 | $(3,6,0)(3,0,1)$ |
| 1.64 | $(3,6,0)(3,0,1)$ |
| 1.96 | $(3,5,0)(3,0,1)$ |
| 2.33 | $(3,5,0)(3,0,1)$ |
| 2.58 | $(3,4,0)(3,0,1)$ |
| 2.81 | $(3,4,0)(3,0,1)$ |
| 3.09 | $(3,3,0)(3,0,1)$ |
| 3.29 | $(3,3,0)(3,0,1)$ |
| 3.72 | $(3,3,0)(3,0,1)$ |
| 4.26 | $(3,2,0)(3,0,1)$ |

The results obtained with the qd-algorithm are the following:

Table q (Statistical significance)

|  | $\mathbf{1}$ | $\mathbf{2}$ | $\mathbf{3}$ | $\mathbf{4}$ | $\mathbf{5}$ | $\mathbf{6}$ |
| :--- | ---: | ---: | ---: | ---: | ---: | ---: |
| $\eta_{0}=$ | -.017 |  |  |  |  |  |
| $\mathbf{0}$ | -.089 |  |  |  |  |  |
| $\mathbf{1}$ | .090 | -.107 |  |  |  |  |
| $\mathbf{2}$ | -.083 | .082 | .416 |  |  |  |
| $\mathbf{3}$ | -5.513 | -.078 | -.048 | .078 |  |  |
| $\mathbf{4}$ | -3.862 | .351 | -.197 | 3.282 | -1.223 |  |
| $\mathbf{5}$ | -2.820 | .651 | -.191 | .164 | .352 | -.241 |
| $\mathbf{6}$ | -2.025 | .187 | -.143 | -.153 | .201 | -.169 |
| $\mathbf{7}$ | -1.601 | .594 | .152 | -.130 | .109 |  |
| $\mathbf{8}$ | -1.209 | -.046 | .559 | -.138 |  |  |
| $\mathbf{9}$ | -.811 | .016 | -.015 |  |  |  |
| $\mathbf{1 0}$ | -.621 | .292 |  |  |  |  |
| $\mathbf{1 1}$ | -.452 |  |  |  |  |  |

The selected models are

| Critical value | Accepted (b,s,r) models |
| :---: | :---: |
| 1.28 | $(3,5,0)(3,0,1)$ |
| 1.64 | $(3,4,0)(3,0,1)$ |
| 1.96 | $(3,4,0),(3,0,1)$ |
| 2.33 | $(3,3,0)(3,0,1)$ |
| 2.58 | $(3,3,0)(3,0,1)$ |
| 2.81 | $(3,3,0)(3,0,1)$ |
| 3.09 | $(3,2,0)(3,0,1)$ |
| 3.29 | $(3,2,0)(3,0,1)$ |
| 3.72 | $(3,2,0)(3,0,1)$ |
| 4.26 | $(3,1,0)(3,0,1)$ |

The comparison among obtained results suggests to accept like probable better model the one corresponding to the orders $(3,0,1)$.

## 5 Conclusions and Open Questions

This paper highlights the usefulness of several numerical methods which are closely related to PA to identify some rational structures associated to data series. This is illustrated in the context of causal time series models, that is, ARMA and TF Models.
The main contribution of this paper is the study of the statistical significance of the rs-algorithm and $q d$ algorithm as a continuation of the work made in González-Gil [16].
Empirical findings points out the role of the statistical significance for the numerical values in the mentioned algorithms. In general, different possible models will be obtained according to certain critical values.
For future research, the generalisation of the results obtained here to VARMA models, in general, is not evident. For example, for the corner method, consideration has to be given to the rank of matrices and non determinants (Pestano-González [22]). Also, the use of matrix epsilon-algorithm has only given partial results (Francq [10]). The generalisation of the rs-algorithm and qd-algorithm has not yet been considered.

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